



Graded Exercise VLSI Design 2019:

SAR ADC

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Successive Approximation ADC

- An Analogue Digital Converter (ADC) converts an analogue value (here a voltage) into a digital (here binary) code.
- An N bit ADC using the 'successive approximation' principle consists of
 - an N bit DAC (Digital Analogue Converter) providing 2^N (voltage) values from (in our case) 0 V to FSR (Full Scale Range)
 - an analogue comparator, comparing the input to the DAC output
 - a (clocked, digital) control logic which observes the comparator output and generates the DAC input word and the result



Operation

- The SAR ADC operates in conversion cycles of N clocks
 - We assume that the input voltage is constant during the cycle (in practice, a Sample-and-Hold may be required at the input to 'freeze' a changing value)
- At the start of a cycle, the logic sets the DAC to $\frac{1}{2}$ FSR
 - The comparator then finds out weather the input V_{in} is larger or smaller than this 'reference'
- At the next clock edge, the logic inspects the comparator output. This is the most significant bit (MSB) of the result.
 - If V_{in} < FSR/2, the logic sets DAC to $\frac{1}{4}$ FSR
 - If $V_{in} \ge FSR/2$, the logic sets DAC to $\frac{3}{4}$ FSR
- At the next clock edge, the next bit is extracted, and the DAC interval is again reduced by half, etc.
- With each clock, the difference between V_{in} and V_{DAC} is reduced to half and one output bit is generated

The Comparator

- We use a very simple comparator with
 - a (PMOS) differential pair
 - followed by a (NMOS) gain stage



The Comparator

- The comparator is biased with a 'not too short' PMOS current source NP1 (L~1µm).
 - Generate the bias voltage pbias by a current mirror!
 - Use a current of for instance 10μ A.
 - For the sake of simplicity, generate the input current to the mirror with a resistor to ground.
- The second stage must be biased with half the current of the first stage so that its threshold is set to the condition V₊ = V₋. Try to understand why!
- This comparator can handle voltages at the inputs from (just) ground up to some positive voltage, but not up to VDD.
- We will therefore restrict the voltage range FSR of our ADC (and thus of the DAC) to this maximal value

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- We use a voltage divider made out of many equal resistors R_A with 2^N taps to generate all possible voltages.
 - Because FSR < VDD, we have an additional resistor R_B
- We then use analogue switches to implement a 2^N→1 MUX which selects one of the voltages, depending on the DAC input code.
 - The MUX may be implemented as a binary tree (a), or using one switch and a decoder per resistor (b)





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THE EXERCISE

Goals for Grading

- In this exercise you should
 - Understand the SAR principle
 - Produce a well structured schematic hierarchy of the design
 - Provide analogue simulations of Comparator and DAC
 - Write a simple Verilog module for the control logic
 - Make a mixed mode simulation which shows correct conversion of a low, a medium and a high input voltage
 - Make 'nice', DRC and LVS error free layouts of Comparator and DAC
- These points should be documented in a short write-up with
 - a text describing your design decisions
 - text and screenshots of the simulation results, answering at least the question raised in the following
 - screenshots and explanations of your schematics layouts

• Use N = 5 or 6.

Exercise 1: Understanding the SAR principle

- Write down the DAC output codes for the conversion sequences of some input voltages.
- Define an algorithm to generate the new DAC control word in the i-th step of the conversion.
- You may want to write a small program the check that you algorithm works

Exercise 2: Simulating the Comparator

- Show that the comparator works:
 - Set one input to a fixed voltage V₁ and sweep (DC or transient) the other input from a bit below V₁ to a bit above V₁.
- Find out and understand for which voltage range of V₁ the comparator works (at decent speed)
 - Try to extend the range as much as you can be sizing the transistors.
 - Make sure V₁ = GND is ok!
 - This fixes the FSR
- Check the speed:
 - The 'precision' of the comparator must only be ~FSR / 2^{N} .
 - We can therefore define a figure of merit for 'speed' as the reaction time for a step input of this size around the threshold.
 - Does speed increase for higher bias current?
 - This speed sets your maximum clocking frequency!!!

Exercise 2 cont.: Simulating the Comparator

- Input offset and common mode effects:
 - Does the comparator really switch *exactly* at V₋ = V₊?
 - Understand what happens!
 - Does this 'input offset' depend on the absolute input voltage level (The 'common mode input voltage') ?
- For our application, the input offset should be smaller than the LSB of our DAC...
 - What is the general effect of input offset on the transfer characteristic of the ADC ?

Exercise 3. Simulating the DAC

- Chose the resistors such that the current in the DAC is not too high (compared to what?)
- Find arguments for the type of decoder to use and implement the schematic
- Simulate (best with a mixed mode simulation) that the decoder works as expected
- How long does it take to stabilize the output voltage for a large voltage step?
 - How does this depend on a load capacitance?
 - Which factors / components limit the speed? How?
 - Is the speed sufficient (compared to the comparator speed) when the capacitive load by the comparator is connected ?

Exercise 4: The full ADC

- Write a Verilog module for the SAR algorithm and simulate the full ADC
 - Make sure the input voltage is stable during one conversion
- Simulate several input voltages in one simulation
 - You may stimulate the input with a piecewise linear voltage source pwl
- You may check that the ADC does not work any more if you run it too fast.
 - You could add an extra capacitance to the DAC output to artificially slow it down.

Exercise 5: Layout

- Make the layout of the DAC such that
 - The resistance can be changed easily
 - The number of bits can be changed easily
- The layout of the DAC should be as compact as possible