



Graded Exercise VLSI Design WS 25/26:

SAR ADC

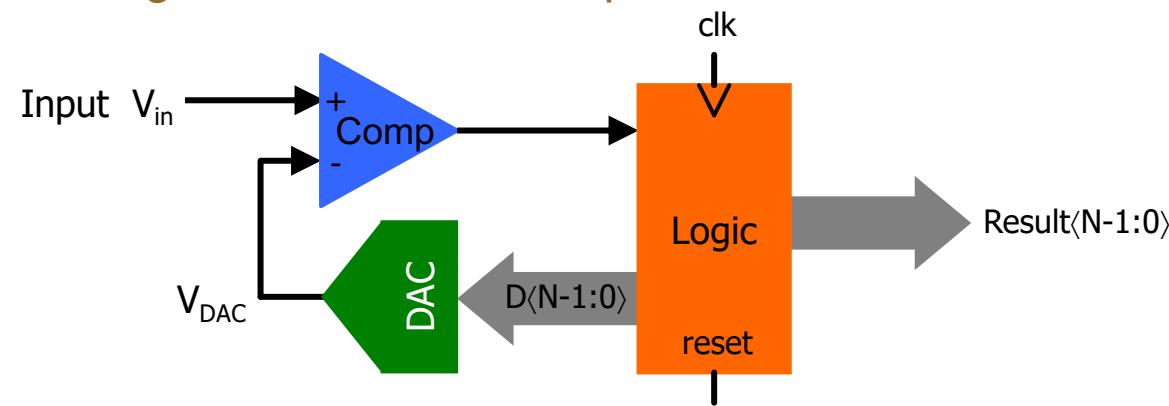
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Successive Approximation ADC

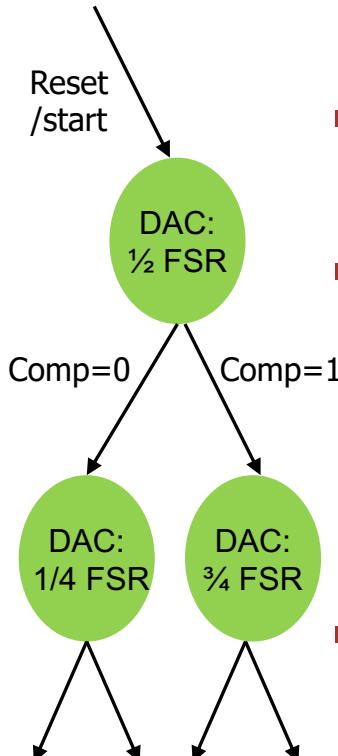
- An Analogue – Digital – Converter (ADC) converts an analogue value (here a voltage) into a digital code (here binary).
- An N bit ADC provides an N bit result, distinguishing 2^N values.
- An N bit ADC using the ‘successive approximation’ (SAR) principle consists of
 - an N bit DAC (Digital – Analogue Converter) providing 2^N (voltage) values from (in our case) 0 V to some FSR (Full Scale Range)
 - an analogue comparator, comparing the input voltage V_{in} to the DAC output
 - a (clocked, digital) control logic which observes the comparator output and generates the DAC input word and the result





Operation

- One SAR conversion cycle requires N steps (clocks)
 - We assume that the input voltage V_{in} is constant during the cycle. In practice, a Sample-and-Hold (S&H) may be required at the input to 'freeze' a changing value.
- At the start of a cycle, the logic sets the DAC to $\frac{1}{2}$ FSR
 - The comparator then finds out whether V_{in} is $>$ or $<$ than $\frac{1}{2}$ FSR
- At the next clock edge, the logic inspects the comparator output (this is the most significant bit (MSB) of the result) and 'calculates' a new DAC value:
 - If $V_{in} < FSR/2$, the logic sets the DAC to $\frac{1}{4}$ FSR
 - If $V_{in} \geq FSR/2$, the logic sets the DAC to $\frac{3}{4}$ FSR
- At the next clock edge, the next bit is extracted, and the DAC interval is again reduced by half, etc.
- With each clock, the difference between V_{in} and V_{DAC} is reduced to half and one more output bit is generated



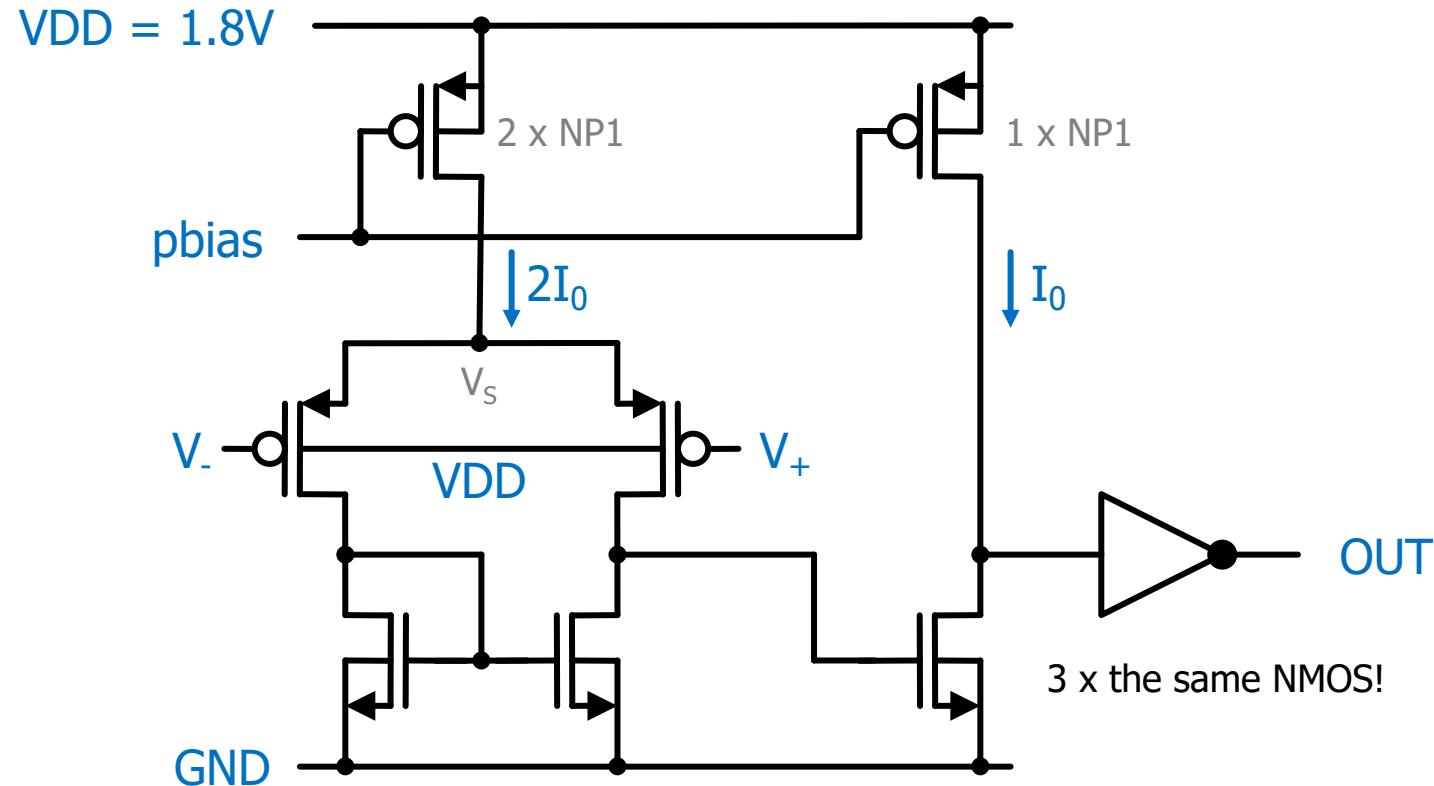


THE BUILDING BLOCKS



The Comparator

- We use a very simple comparator (see CCS!) with
 - a (PMOS) differential pair
 - followed by a (NMOS) gain stage





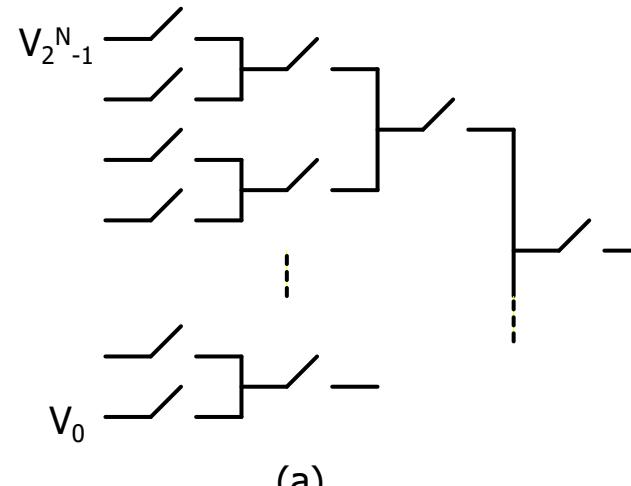
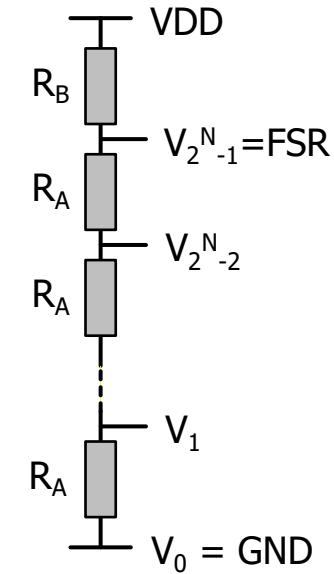
The Comparator

- The comparator is biased with a PMOS current source
 - Generate the bias voltage p_{bias} by a current mirror!
 - Use a current of – for instance – $10\mu A$.
 - For the sake of simplicity, generate the input current to the mirror with a resistor to ground.
- The second stage must be biased with *half the current* of the first stage so that its threshold is reached for $V_+ = V_-$. Try to understand why!
 - This is achieved by using two PMOS for the differential pair, one for the second stage
- This comparator can handle voltages at its inputs from (just) ground up to *some* positive voltage, but not up to VDD .
 - Why does it help to connect the bulks of the pair to VDD ?
- We therefore restrict the voltage range of our ADC (and thus of the DAC) to this maximal value 'Full Scale Range' FSR.

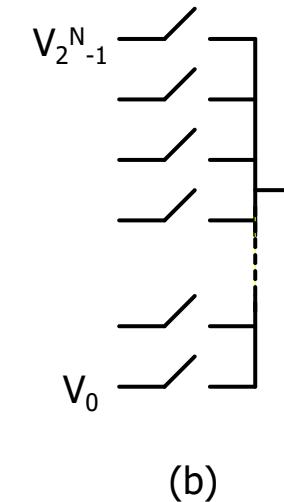


The DAC

- We use a voltage divider made out of 2^N-1 equal resistors R_A to generate all possible 2^N voltages.
 - We obtain $FSR < VDD$ by an additional resistor R_B
- We then use analogue switches to implement a $2^N \rightarrow 1$ MUX which selects one of the voltages, depending on the DAC input code.
 - The MUX may be implemented as a binary tree (a), or using '1 hot encoded' switches to a bus (b)



(a)



(b)



THE GRADED EXERCISE



Task and Criteria for Grading

- In this exercise you should
 - Understand the SAR principle
 - Produce a well-structured *schematic hierarchy* of the design
 - Provide *analogue simulations* of comparator and DAC
 - Write a simple Verilog module for the control logic
 - Make a *mixed mode simulation* which shows correct conversion of a low, a medium and a high input voltage
 - Make DRC / LVS error-free *nice, compact layouts* of Comp. and DAC
- This should be documented in a write-up (~15-20 pages) with
 - An explanation and illustration of the SAR principle
 - A text justifying your design decisions
 - Text and screenshots of the simulation results, answering at least the question raised on the following slides
 - Screenshots and explanations of your schematics and layouts
- Use at least $N = 5$, better more
 - Ideally schematics and layout can be easily scaled to larger N



General

- We use UMC180 nm
- Operate at 1.8V
- Start with MOS of 10u/0.5u for the comparator (quite large...). You can try to optimize later.
- Use small MOS for the decoder to limit capacitance, but estimate that their resistance is no issue.

- In the layout, try to match devices where necessary. You may want to place dummy devices where matching is relevant.



Part 1: Understanding the SAR principle

- Write down the DAC output codes for the conversion sequences of some input voltages.
- Find an algorithm / formula to generate the new DAC control word in the i -th step of the conversion.

- You may want to write a small program to check that your algorithm works. Try it on several cases!



Part 2: Simulating the Comparator

- Show that the comparator works:
 - Set one input to a fixed voltage V_1 and sweep (DC or transient) the other input from a bit below V_1 to a bit above V_1 .
- Find out and understand for which voltage range of V_1 the comparator works (at decent speed)
 - Understand what limits the range (to low and high voltages!)
 - (Try to extend the range by sizing the transistors)
 - Make sure $V_1 = \text{GND}$ is ok!
 - This fixes the FSR. Use a safe value.
- Determine the input offset voltage, i.e. at which input voltage difference the comparator switches.
 - Try different common mode voltages V_{CM} (as we will have them in the SAR application)
 - Verify that the input offset becomes worse if the 3 NMOS have not identical size or if the PMOS currents are not 2:1
 - Is the input offset small enough? Compare it to the LSB. What happens to the ADC if we have a fixed offset (independent of V_{CM})?



Part 2: Simulating the Comparator

- Check the speed:

- The ‘precision’ of the comparator must ‘only’ be $\sim \text{FSR} / 2^N$.
- We can therefore define a figure of merit for ‘speed’ as the reaction time for a step input of this size around the threshold.
- Does speed increase for higher bias current?
- This speed sets your maximum clocking frequency!!!



Part 3: Simulating the DAC

- Chose the resistors such that the current in the DAC is not too high (compared to what?). Think at the layout size as well!
- Find arguments for the type of decoder to use and implement the schematic. Also think how a nice layout could look (also for large N)
- What type of MOS can be used for the switches? Or should you better use transmission gates?
- Use one switch and a decoder or multiple serial MOS to do the decoding?
- Simulate (best with a mixed mode simulation) that the decoder (and DAC) work as expected
- How long does it take to stabilize the output voltage for a large voltage step?
 - How does this depend on a load capacitance?
 - Which factors / components limit the speed? How?
 - Is the speed sufficient (compared to the comparator speed) when the capacitive load by the comparator is connected ?



Part 4: The full ADC

- Write a Verilog module for the SAR algorithm and simulate the full ADC
 - Make sure in your simulation that the input voltage is stable during one conversion
- Simulate several input voltages in one simulation
 - You may stimulate the input with a piecewise linear voltage source pwl, or superimpose voltages of several vpulse sources
 - You may also use ocean to script the simulation and then let it run for many voltages (smaller than the resolution).
- You may check that the ADC does *not* work any more if you run it too fast.
 - You could add an extra capacitance to the DAC output to artificially slow it down.



Part 5: Layout

- Make the layout of the DAC (with switches) such that
 - The resistance value can be changed easily without the need to re-do large parts
 - The number of bits can be increased relatively easily
- The layout of the DAC should
 - be reasonably compact
 - Not have an extreme aspect ratio, i.e. should be roughly square
- It may be clever to make a ‘unit cell’ which contains resistor and switch
- Your layout should be ‘regular’ for good matching of the resistors. You may even want to use dummy resistors at the ‘ends’.
- Add the layout of the compactor and make the LVS